





Horizon 2020 European Union funding for Research & Innovation

# **CERBERO**

(Cross-layer modEl-based fRamework for multi-oBjective dEsign of Reconfigurable systems in unceRtain hybRid envirOnments) OCEAN MONITORING USE CASE

AmbieSense: Leszek Kaliciak, Hans Myrhaug, Ayse Goker, Stuart Watt

http://www.cerbero-h2020.eu/





## **CERBERO** Goals

Main project goals of CERBERO Ocean Monitoring use-case are:

- Validate CERBERO methodology for development of multi-objective adaptive CPS
- Contribute to development of CERBERO technologies for development of multi-objective adaptive CPS
- Validate developed KPI based adaptation loop







### **AS Goals**

- Hierarchical adaptive system design:
  - Advanced visual sensing for both users and for marine robots.
  - Visual quality most important for users/ human operators.
  - Sensing of the environment is key for autonomous navigation.
- Purpose:
  - To automatically enhance visibility for the users.
  - To enable autonomous navigation obstacle detection, sense environment, distance to objects nearby.
  - To extend the range of marine robots day&night, depth.







# The OM solution

Adaptive cameras Embedded sensors and monitoring

**Umbilical cables** 

**Cloud** Data archiving Hub alternative for always-on environments

Monitoring hub Underwater video

**Underwater ROVs** Open platform for adaptive cameras and sensors Underwater video enhancement Image indexing and data logging Monitoring and alerting





#### Use case development

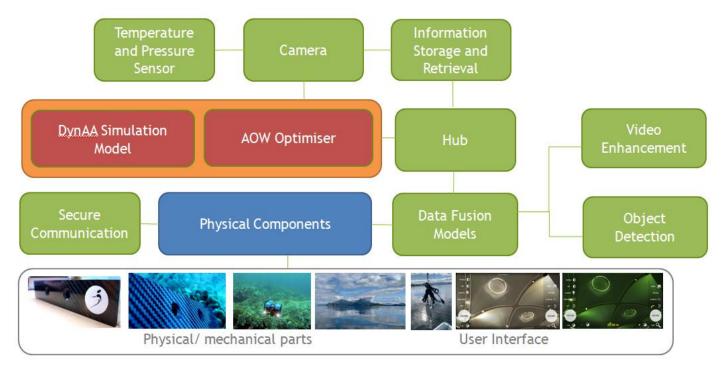
Steps in the development of the use case:

- Requirements gathering
- Development of **adaptation approaches** with **scenarios** which require adaptation (initiated by human and environmental triggers)
- Extend CERBERO technologies by development of information fusion technologies to enable adaptation and support the use case
- Integrate CERBERO tools and technologies into Ocean Monitoring





#### **Skeleton of CERBERO tools for Ocean Monitoring use case**

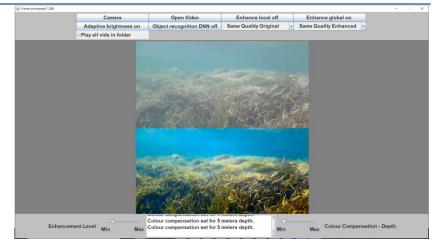






#### **CERBERO Fusion Technologies to enable** adaptation:

- Image enhancement level adaptation to different environmental conditions
- Colour adaptation to changing water depth
- Adaptation of object characteristics for tracking purposes based on motion and deep learning detector









#### **DynAA** and **AOW**:

- DynAA helped to assess alternative design configuration choices to ensure that the chosen hardware platform met the required KPIs
- AOW helps to optimise the image enhancement model. It can be used to adaptively select the appropriate combination of algorithms to ensure the best result dynamically.

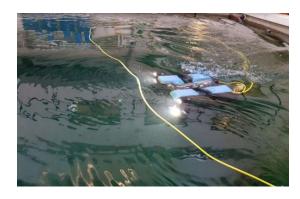




# **OM Testing:**

- Pool testing
- Pressure chamber
- Arctic Ocean











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# M36 DEMONSTRATOR