

Coarse-Grained Reconfiguration: Run-time Adaptivity in Cyber Physical Systems

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Outline

- Introduction
 - CERBERO and Cyber Physical Systems
 - HEVC Codec and Software Approximate Computing
- Approximate HEVC interpolators
 - Coarse-Grained Reconfiguration
 - From CG HEVC Interpolators to CGR HEVC Interpolators
- Results
 - Achieved Adaptivity
 - Comparison with the State of the Art
- Conclusions

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CERBERO project

Cross-layer model-based framework for multi-objective design of Reconfigurable systems in uncertain hybrid environments

→ continuous design environment for **Cyber-Physical Systems (CPS)** including modelling, deployment and verification



Self-healing system for planetary exploration



Smart Travelling for Electric Vehicle



Oceans Monitoring



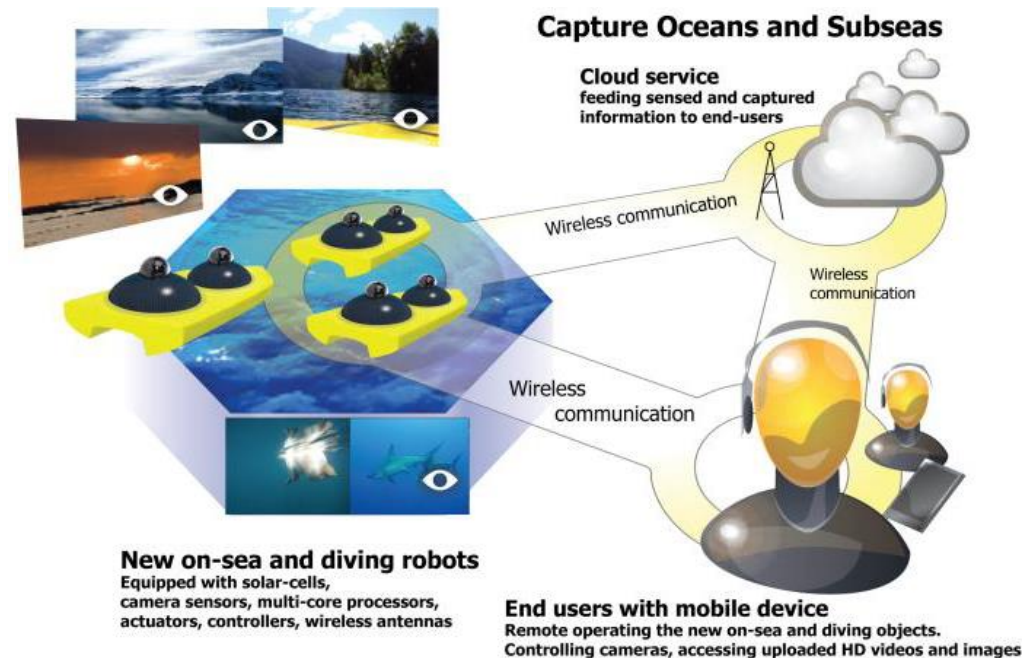
Cyber Physical Systems (CPS)

Complex systems with **different interacting and deeply intertwined components**, providing multiple and distinct **behavioral modalities** potentially **changing over time**, that contribute **concurrently** to determine the behavior of the system as a whole.

Layers (dominant aspects):

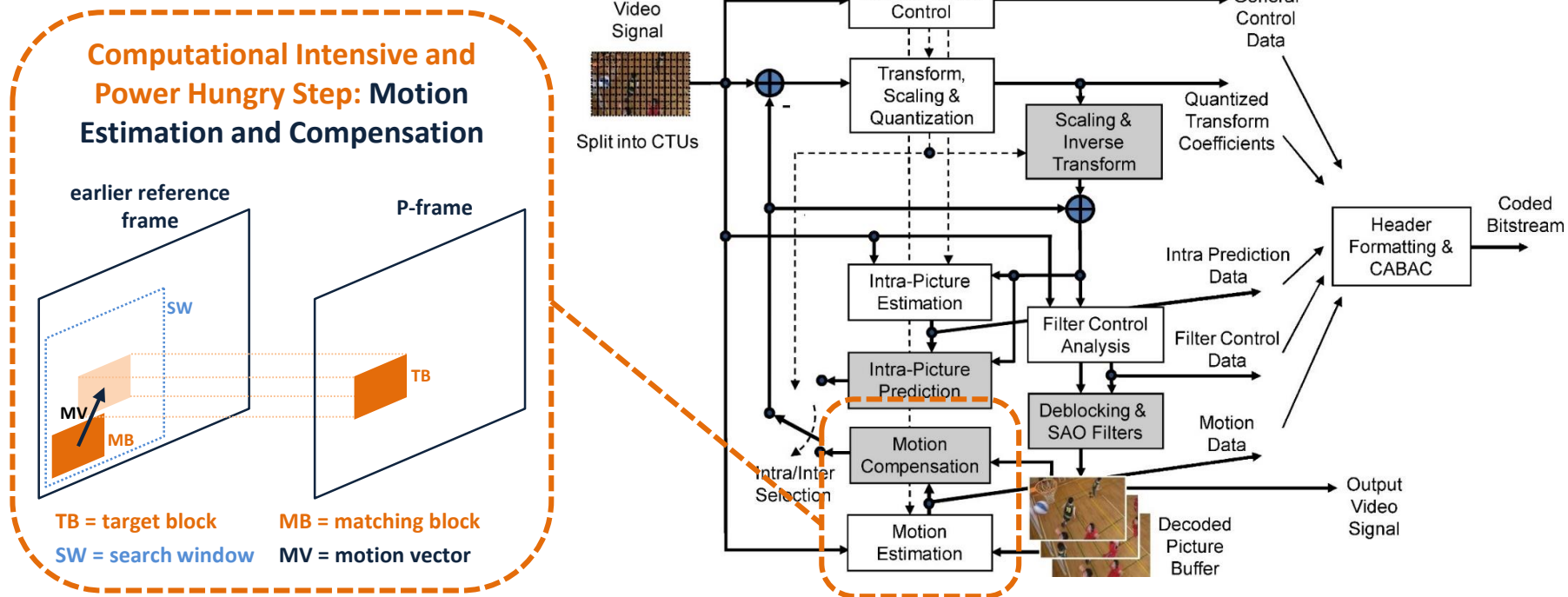
- functional
- physical
- communication

Subjected to **Functional** (F) and **Non-Functional** (NF) requirements variation in time.



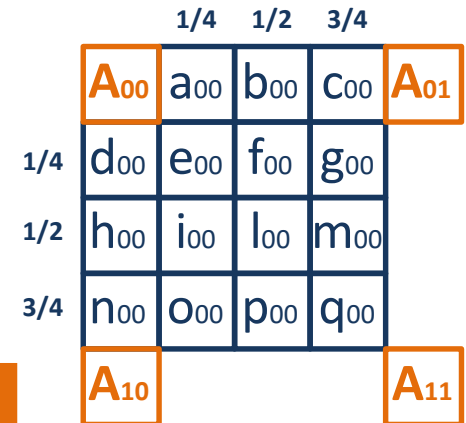
High Efficiency Video Coding (HEVC)

Recent video codec developed by the Joint Collaboration Team on Video Coding (VCEG and MPEG). It provides up to **50% bit rate reduction at the same subjective video quality** with respect to previous standards (H.264).



Approximate HEVC Interpolation in Software

With high frame rates the **motion vector** could be composed of **fractional pixel** values. In these cases an **interpolation (FIR filtering)** of the matching block is necessary.



| luma MV α | legacy | approximate [1] | | | | |
|---------------------|--------------------------------|---------------------------|-------------------|------------|-------|--|
| | 8/7 tap | 7 tap | 5 tap | 3 tap | 1 tap | |
| 1/4, 3/4 | -1, 4, -10, 58, 17, -5, 1 | -1, 4, -10, 58, 17, -5, 1 | 1, -6, 20, 54, -5 | -4, 20, 48 | 64 | |
| 1/2 | -1, 4, -11, 40, 40, -11, 4, -1 | -1, 4, 11, 40, 40, -11, 3 | 2, -9, 40, 40, -9 | -9, 41, 32 | 64 | |

| chroma MV α | legacy | approximate [1] | | |
|-----------------------|----------------|-----------------|--------|-------|
| | 4 tap | 3 tap | 2 tap | 1 tap |
| 1/8, 7/8 | -2, 58, 10, -2 | -3, 62, 5 | 58, 7 | 64 |
| 1/4, 3/4 | -4, 54, 16, -2 | -5, 58, 11 | 50, 15 | 64 |
| 3/8, 5/8 | -6, 46, 28, -4 | -7, 51, 20 | 41, 23 | 64 |
| 1/2 | -4, 36, 36, -4 | -6, 42, 28 | 32, 32 | 64 |

→ up to **28% energy saving** with a **small degradation** of decoding quality on an ARM big.LITTLE SoC

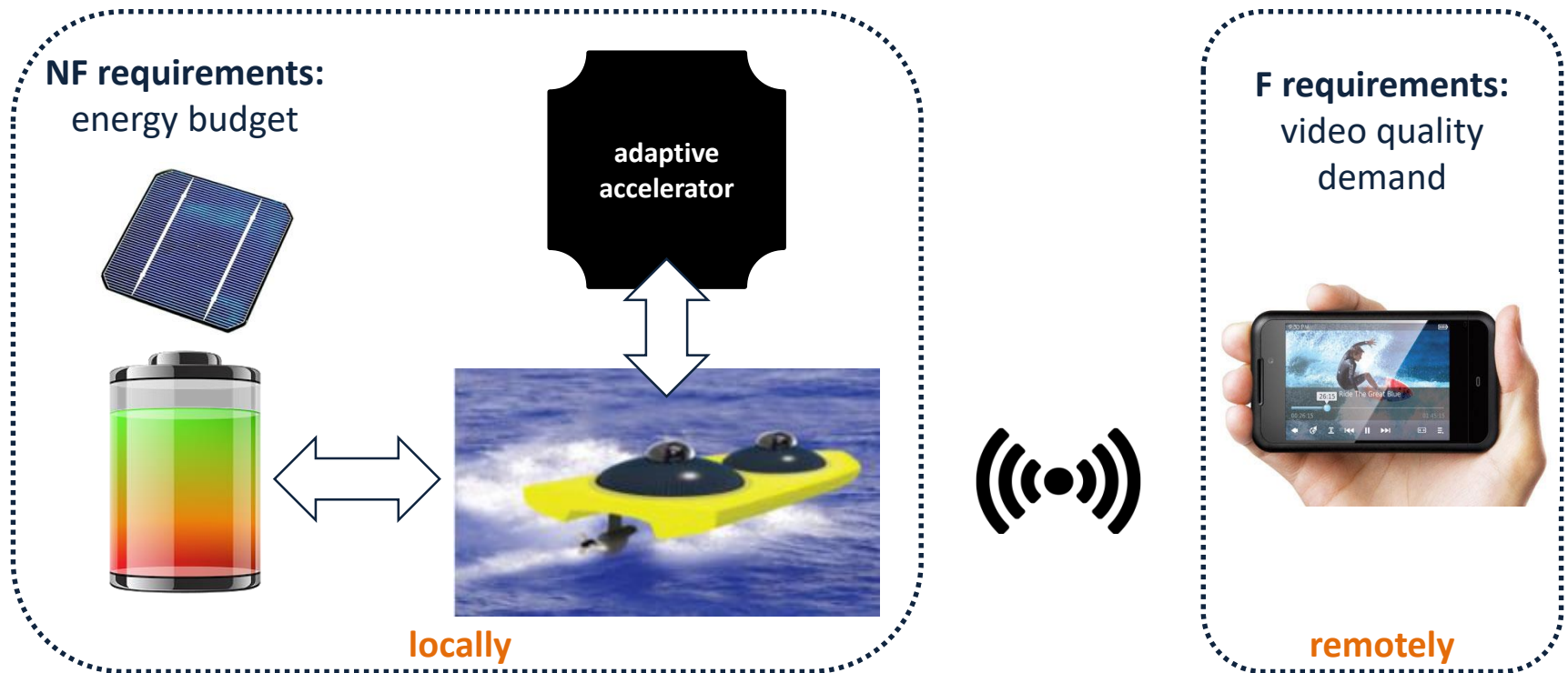
[1] E. Nogues et al., "Algorithmic-level approximate computing applied to energy efficient hevc decoding," IEEE Trans. On Emerging Topics in Computing, 2016.

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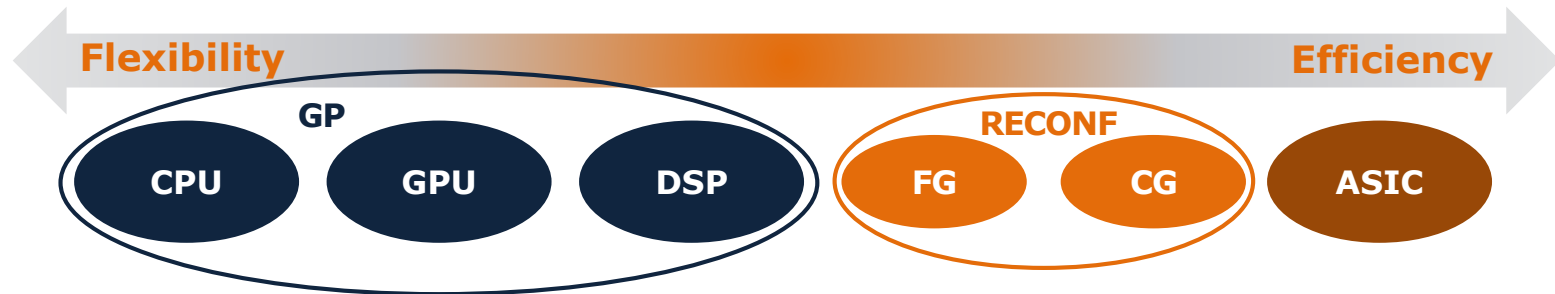
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Run-time Adaptivity in CPS

At the CPS physical level **application specific efficient accelerators** capable of providing **flexibility and dynamic adaptation to changeable F/NF requirements**.



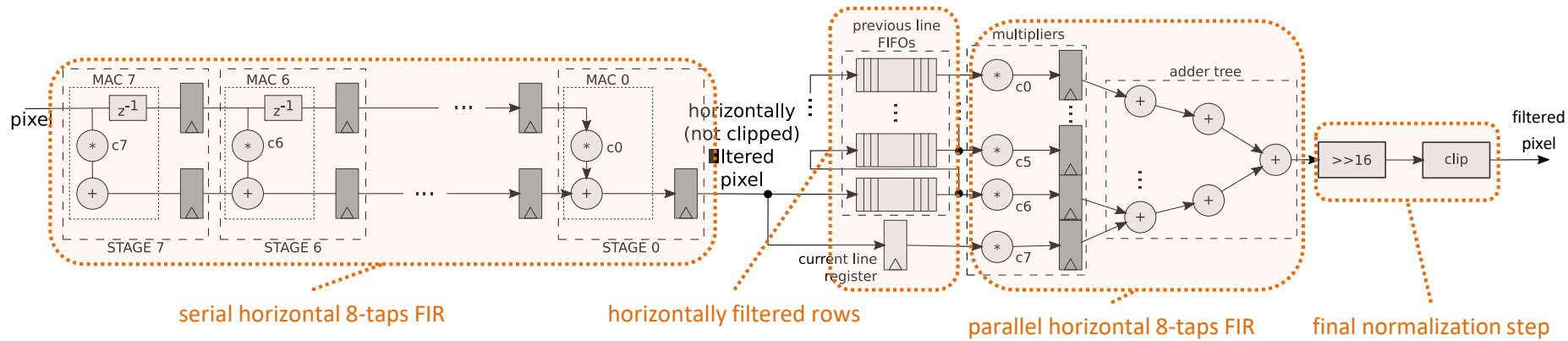
Coarse-Grained Reconfiguration (CGR)



Reconfigurable computing provides a **trade-off between execution efficiency** typical of ASICs **and flexibility** mainly exhibited by GP devices.

| | Fine-Grained (FG) bit-level | Coarse-Grained (CG) word-level |
|-------------|--------------------------------|-----------------------------------|
| flexibility | 😊 | 😐 |
| speed | 😐 | 😊 |
| memory | 😞 | 😐 |

CG HEVC interpolators



example N=4

$$y_3 = c_0x_2 + c_1x_3 + c_2x_4 + c_3x_5$$

$$y_2 = c_0x_1 + c_1x_2 + c_2x_3 + c_3x_4$$

$$y_1 = c_0x_0 + c_1x_1 + c_2x_2 + c_3x_3$$

$$z_9 = c_0y_1 + c_1y_9 + c_2y_{17} + c_3y_{25}$$

$$z_{10} = c_0y_2 + c_1y_{10} + c_2y_{18} + c_3y_{26}$$

$$z_{11} = c_0y_1 + c_1y_9 + c_2y_{17} + c_3y_{25}$$

$X_{8 \times 8}$

| | | | | | | | |
|----|----|----|----|----|----|----|----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
| 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 |
| 24 | 25 | 26 | 27 | 28 | 29 | 30 | 31 |
| 32 | 33 | 34 | 35 | 36 | 37 | 38 | 39 |
| 40 | 41 | 42 | 43 | 44 | 45 | 46 | 47 |
| 48 | 49 | 50 | 51 | 52 | 53 | 54 | 55 |
| 56 | 57 | 58 | 59 | 60 | 61 | 62 | 63 |

→
horizontal
Filtering
(N-1 cols)

$Y_{8 \times 5}$

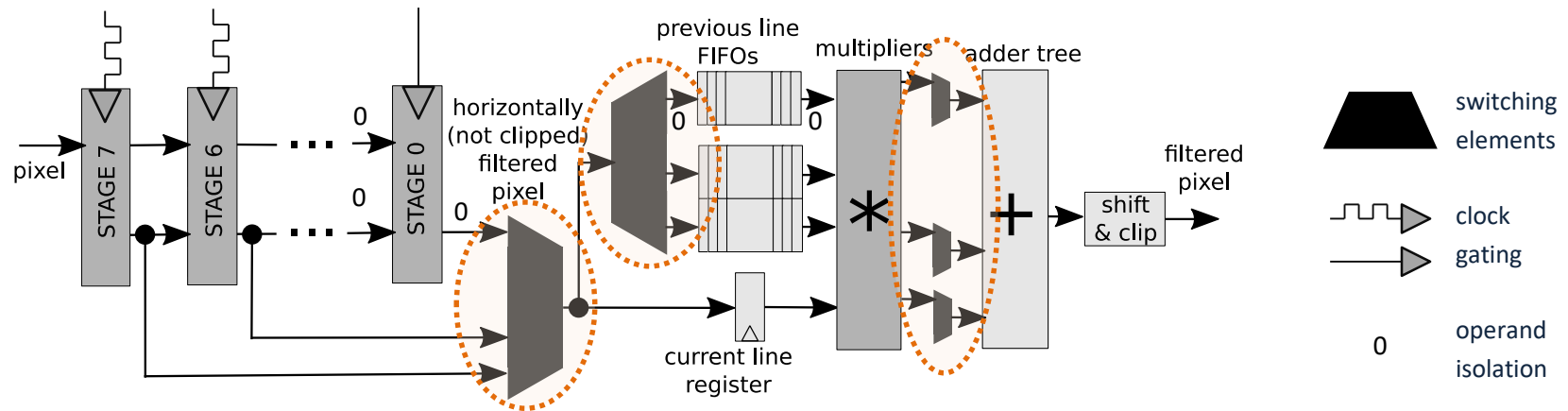
| | | | | | | | |
|---|----|----|----|----|----|---|---|
| - | 1 | 2 | 3 | 4 | 5 | - | - |
| - | 9 | 10 | 11 | 12 | 13 | - | - |
| - | 17 | 18 | 19 | 20 | 21 | - | - |
| - | 25 | 26 | 27 | 28 | 29 | - | - |
| - | 33 | 34 | 35 | 36 | 37 | - | - |
| - | 41 | 42 | 43 | 44 | 45 | - | - |
| - | 49 | 50 | 51 | 52 | 53 | - | - |
| - | 57 | 58 | 59 | 60 | 61 | - | - |

→
vertical
Filtering
(N-1 rows)

$Z_{5 \times 5}$

| | | | | | |
|---|----|----|----|----|----|
| - | - | - | - | - | - |
| - | 9 | 10 | 11 | 12 | 13 |
| - | 17 | 18 | 19 | 20 | 21 |
| - | 25 | 26 | 27 | 28 | 29 |
| - | 33 | 34 | 35 | 36 | 37 |
| - | 41 | 42 | 43 | 44 | 45 |
| - | - | - | - | - | - |
| - | - | - | - | - | - |

CGR HEVC interpolators



| profile | HIGH | | | MEDIUM | | | LOW | | |
|---------|---------|--------|--------|---------|--------|--------|---------|--------|--------|
| | quality | # taps | energy | quality | # taps | energy | quality | # taps | energy |
| luma | 😊 | 8/7 | 😞 | 😐 | 5 | 😐 | 😞 | 3 | 😊 |
| chroma | | 4 | | | 3 | | | 2 | |

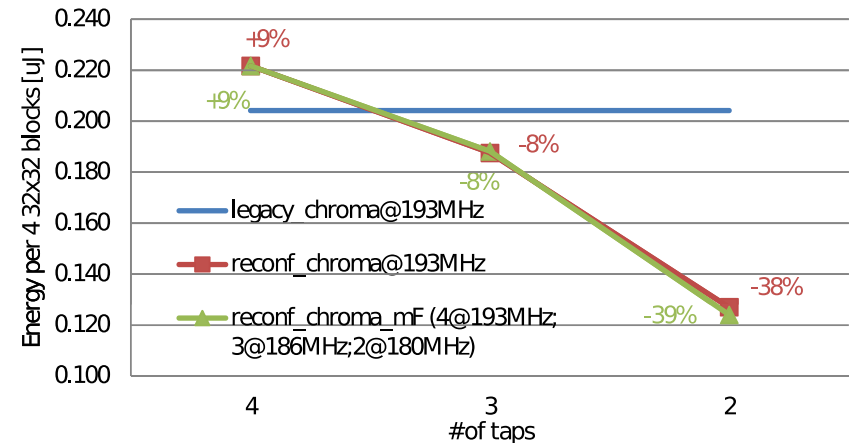
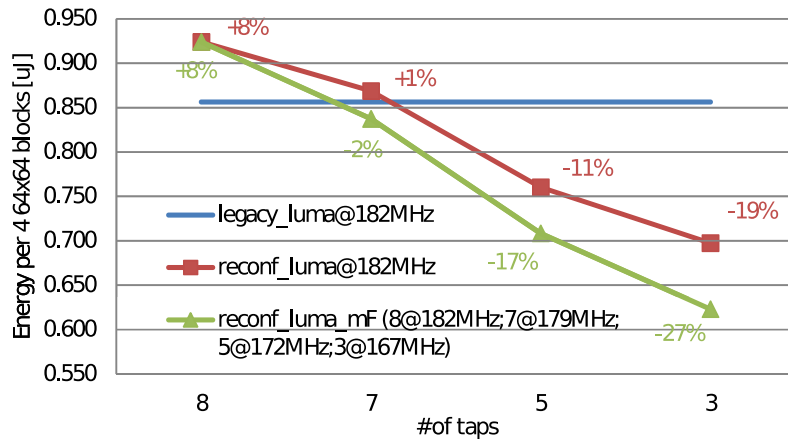
[2] F. Palumbo et al., "Runtime energy versus quality tuning in motion compensation filters for HEVC," *Proc. of the PDeS Conf.*, 2016.

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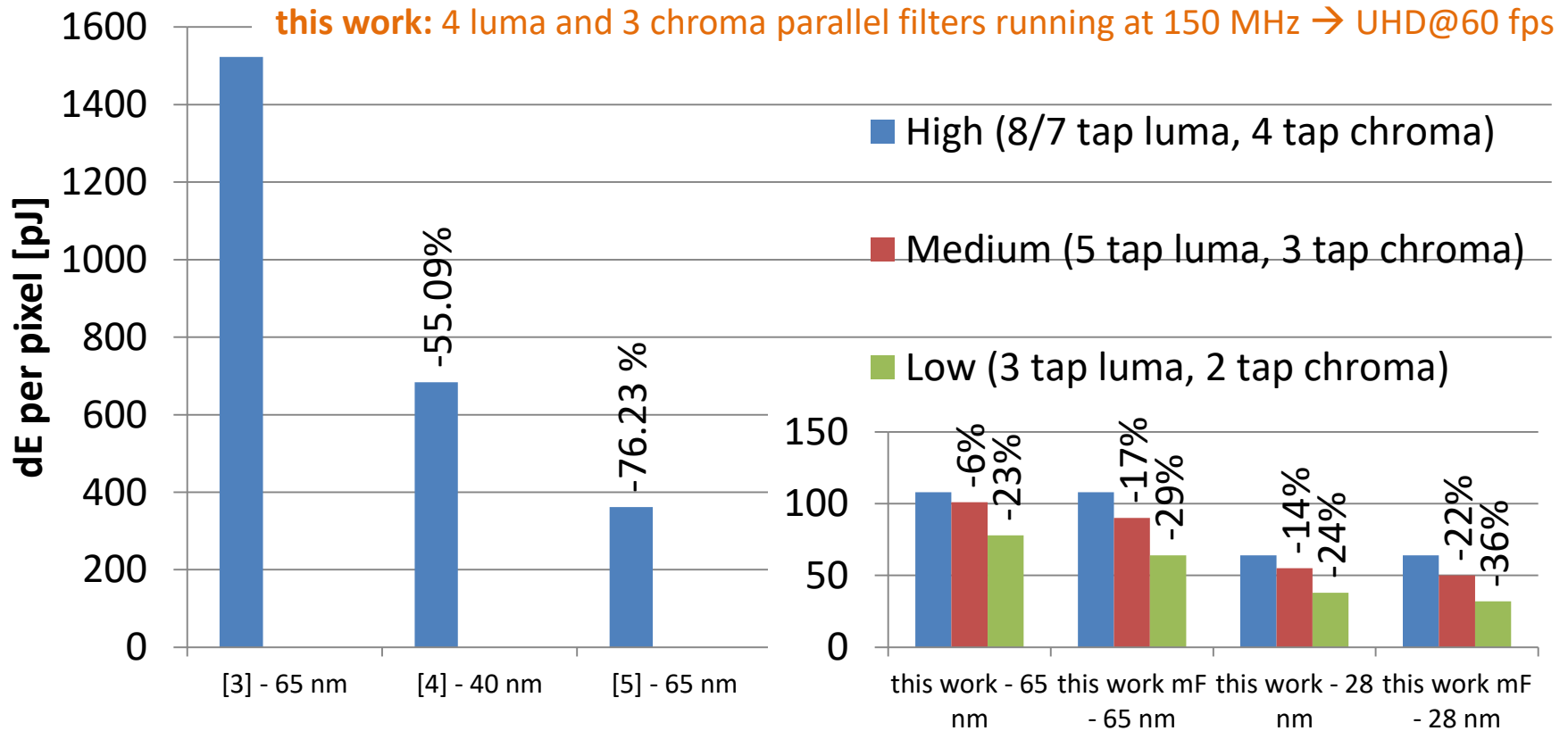
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Achieved Adaptivity

| design @200 MHz Xilinx XC7Z020 | LUT | FF | BRAM | DSP | Fmax [MHz] | tap | dP (Vivado) [mW] | dE [μJ] | time per block [cycles] | # interpolated pixels in a fixed time |
|-----------------------------------|----------------|---------------|------------|-------------|---------------|-----|---------------------|--------------|----------------------------|--|
| legacy_luma | 212 | 37 | 4 | 16 | 213 | 8 | 11 | 0.248 | 460 | 57957 |
| reconf_luma (vs legacy %) | 582 (+175%) | 85 (+130%) | 4 (+0%) | 16 (+0%) | 200 (-6%) | 8 | 12 (+9%) | 0.270 (+9%) | 460 (+0%) | 57957 (+0%) |
| | | | | | | 7 | 11 (+0%) | 0.245 (-1%) | 395 (-14%) | 59033 (+2%) |
| | | | | | | 5 | 10 (-9%) | 0.217 (-12%) | 265 (-42%) | 61191 (+6%) |
| | | | | | | 3 | 10 (-9%) | 0.211 (-15%) | 135 (-71%) | 63357 (+9%) |
| legacy_chroma | 163 | 33 | 2 | 8 | 217 | 4 | 9 | 0.053 | 107 | 14753 |
| reconf_chroma (vs legacy %) | 383 (+135%) | 65 (+97%) | 2 (+0%) | 8 (+0%) | 200 (-12%) | 4 | 9 (+0%) | 0.053 (+0%) | 107 (+0%) | 14753 (+0%) |
| | | | | | | 3 | 8 (-11%) | 0.045 (-13%) | 73 (-32%) | 15293 (+4%) |
| | | | | | | 2 | 6 (-33%) | 0.033 (-37%) | 39 (-64%) | 15835 (+7%) |



Comparison with the State of the Art



[3] V. Afonso et al., "Low cost and high throughput FME interpolation for the HEVC emerging video coding standard," *Proc. of the IEEE LASCAS Conf.*, 2013.

[4] E. Kalali et al., "A reconfigurable HEVC sub pixel interpolation hardware," *Proc. of the IEEE ICCE Conf.*, 2013.

[5] C. M. Diniz et al., "A reconfigurable hardware architecture for fractional pixel interpolation in high efficiency video coding," *IEEE Comput.-Aided Des. Integr. Circuits Syst.*, vol. 34, no. 2, pp. 238–251, 2015.

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Conclusions

- **CERBERO**: continuous design environment for **Cyber-Physical Systems** (CPS)
 - run-time F/NF requirements driven adaptivity
- **HEVC** power/energy hungry, latest video coding standard
 - **Approximate computing** on HEVC interpolators demonstrated to provide energy versus quality trade-off
- **Coarse-Grained Reconfiguration** (CGR) allows approximation of HEVC interpolators in hardware
 - our solution challenges outperforms state of the art solutions
- Future directions on:
 - adopt a **multiplier-less** solution to further reduce consumption
 - embedding the **whole HEVC codec on FPGA** (software/hardware)

CPS Summer School 2017



Porto Conte Ricerche, Alghero (Italy) – September 25-30, 2017

Designing Cyber-Physical Systems – From concepts to implementation

Multi-objective Methodologies and Tools for Self-healing and Adaptive Systems

Distinguished lecturers: Alberto Sangiovanni-Vincentelli, Hironori Kasahara,
Muhammad Shafique

Application deadline: July 7th, 2017

<http://www.cpsschool.eu/>

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The CERBERO project has received funding from the EU Commission's H2020 Programme under grant agreement No 732105.



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